

VIRTUAL TIRE DEVELOPMENT FOR NEW ELECTRIC VEHICLE THROUGH DRIVER IN LOOP

RUTGER UIL – THE GOODYEAR TIRE & RUBBER COMPANY
GUIDO TOSOLIN – APPLUS IDIADA

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CONTENTS

1. Introduction to Mahindra INGLO Platform
2. Virtual development methodology
3. Real-Time virtual models
 - Vehicle Model Generation - ADAMS to CRT Process
 - Tire Model Generation
4. Virtual development loops
5. Validation & Conclusions



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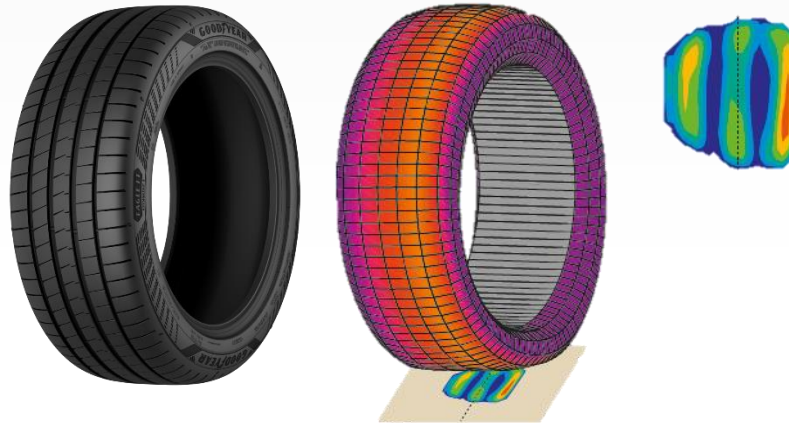
INTRODUCTION

Performance Requirements



Mahindra 'INGLO'
New BEV platform

Tire Virtual Development



Virtual Tire Development
Virtual modelling & assessment

Development Validation



Driving Simulator
Virtual Evaluation Capability



MAHINDRA INGLO PLATFORM | ELECTRIC SUVS



PLATFORM HIGHLIGHTS

- Common & Modular
- 5 Different top hats
- 250+ kW dual motors
- 10.2 m TCD
- Up to 78 kWh battery
- 5 / 7 - seater



MAHINDRA INGLO PLATFORM | PERFORMANCE CHALLENGES



High RAW & CoG



Best in Class Range



Sporty Handling



Variety Road Profile

Low RRC
Low Tire Noise
Best in Class Ride and Handling



Plush Ride-comfort





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OVERALL DEVELOPMENT PLAN | VEHICLE DYNAMICS

Benchmarking &
Target Setting

Soft-tool
Prototypes

Hard-tool
prototypes

~~Mule Validation
and Tuning~~



Critical design decisions, normally supported by physical mule testing, to be taken with the use of driving simulator technology, including tire development.

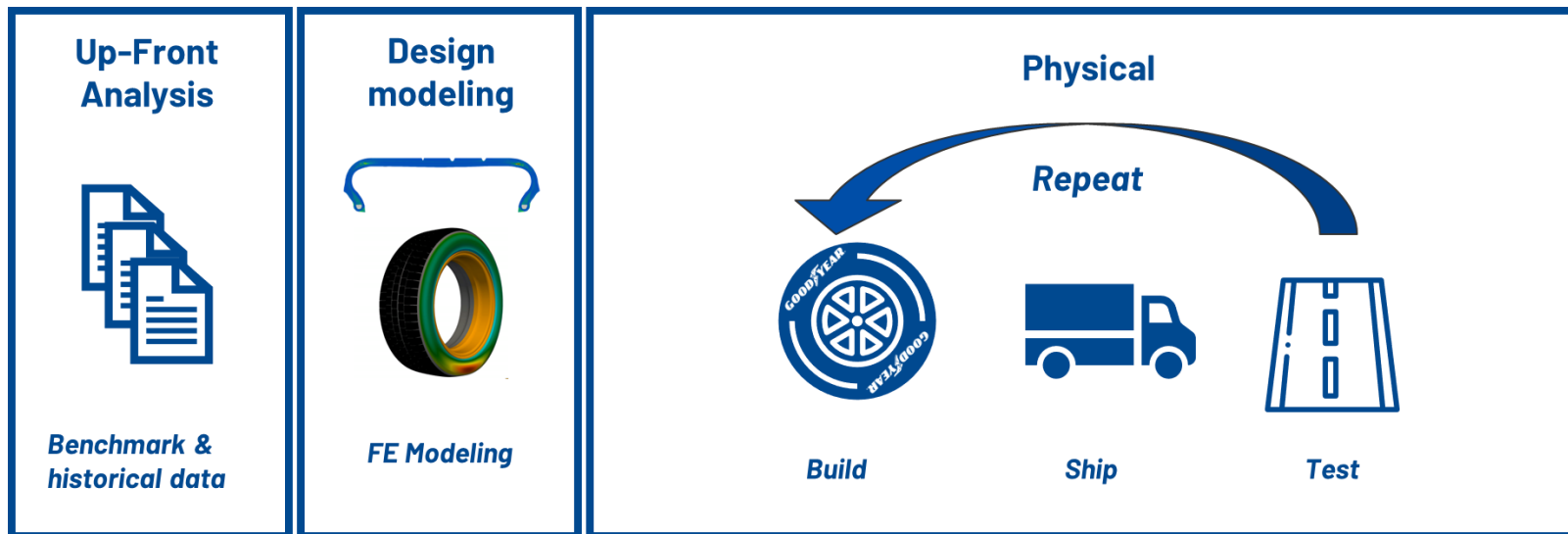


PHYSICAL DEVELOPMENT | PHYSICAL TIRE RIDE AND HANDLING

Definition: Actual prototype vehicles with latest suspension, brakes, steering parts are build to meet the vehicle ride quality and vehicle handling requirements. Subsequently, the tire submissions are subjectively evaluated on real test tracks.



Traditional approach – Vehicle Prototype + Physical Tire Submissions + Assessment

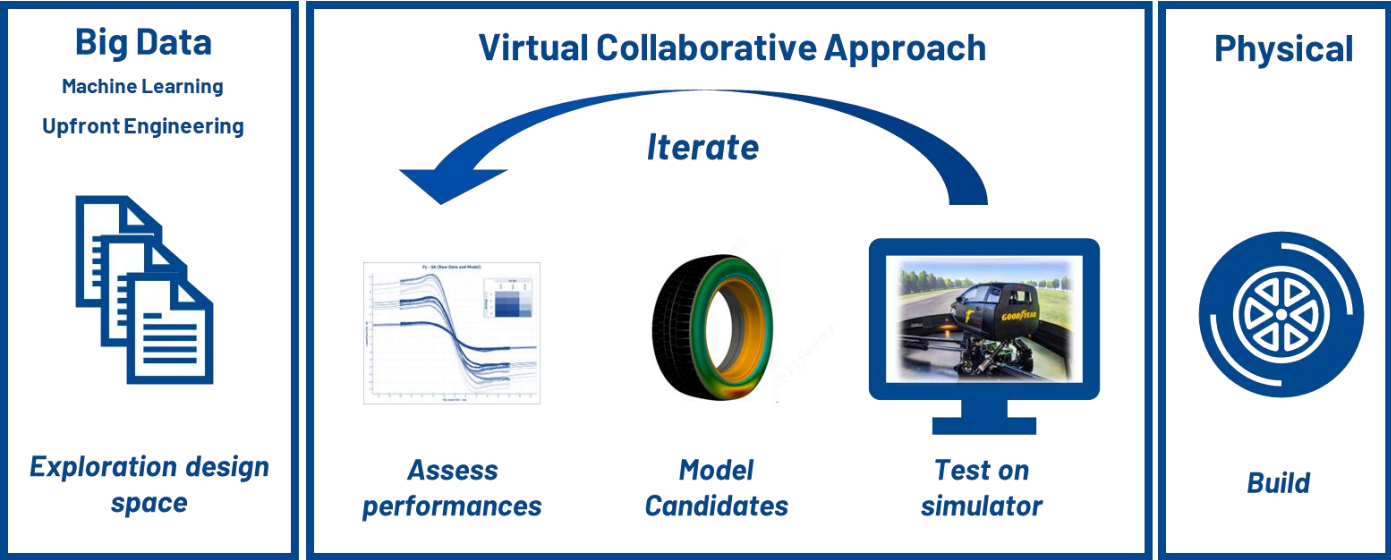


VIRTUAL DEVELOPMENT | VIRTUAL TIRE RIDE AND HANDLING

Definition: Driving simulator is setup with latest vehicle component configurations via real-time models. In addition, virtual tire candidates enable drivers to perform a complete subjective evaluation in virtual scenarios.



Virtual approach – Real-Time Vehicle Models + Virtual Tire Models + Assessment

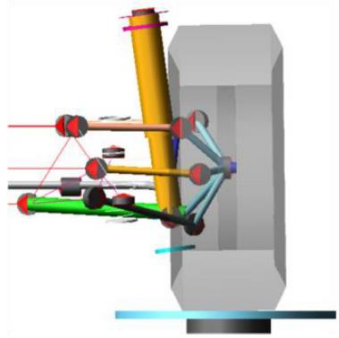




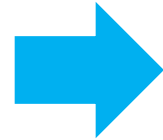
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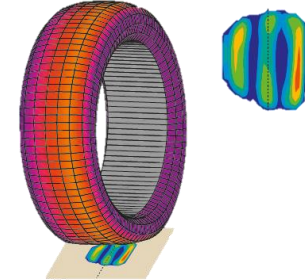
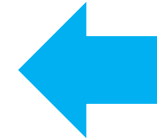
REAL-TIME MODELS | VEHICLE MODEL GENERATION



MBD model
(ADAMS Car)



Real-time vehicle model
(VI-CRT)



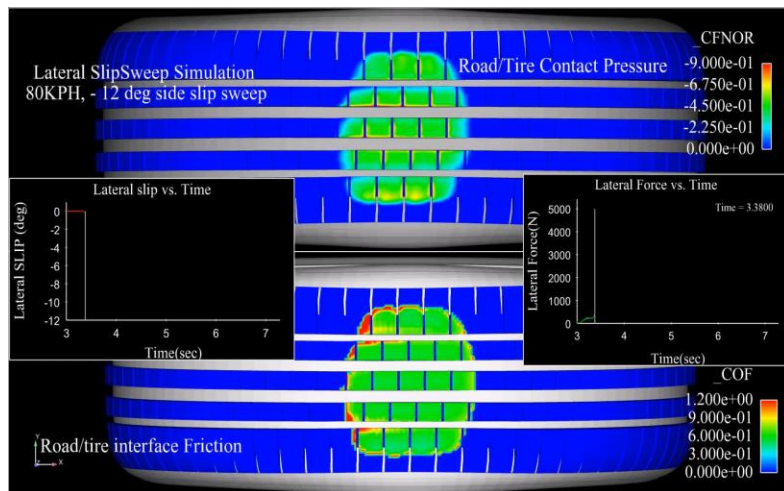
Physical tire model
(CDTire/RT)



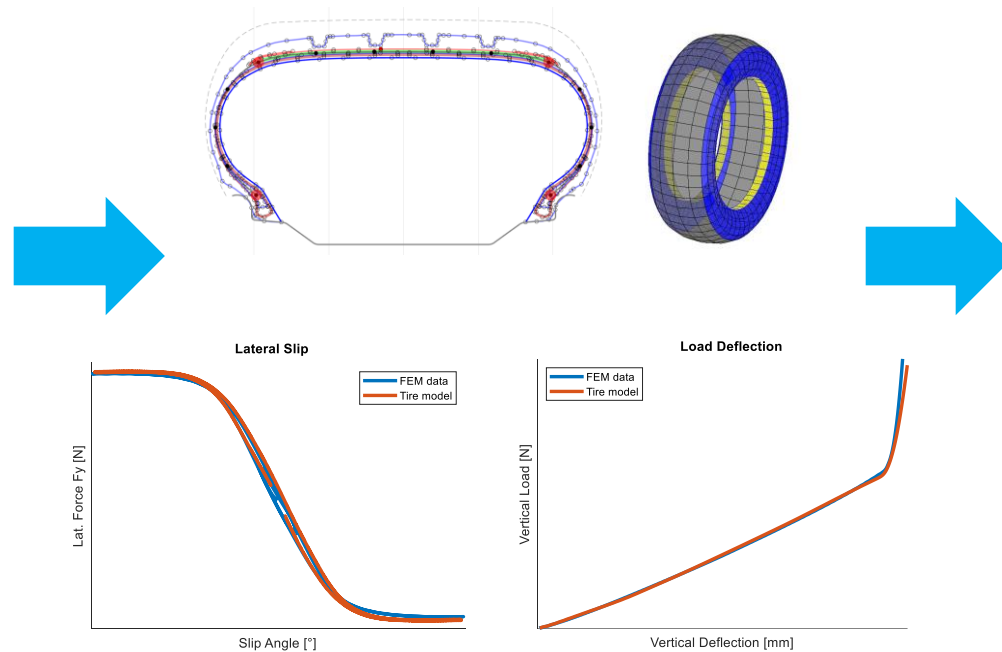
Driver-in-Loop simulator
(VI-Grade DiM250)



FE Simulations



Virtual Candidates



Driver-in-Loop Simulator



PHYSICAL TIRE MODELS DERIVED FROM FE SIMULATIONS AND CONVERTED IN REAL-TIME CAPABLE MODELS FOR THE ASSESSMENT OF THE VIRTUAL TIRE PERFORMANCE



REAL-TIME MODELS | EVALUATION SCENARIOS

Attributes

Limit Handling Stability
Understeer character



Steering feel
Cornering confidence
Lane change stability



Primary body motions
Suspension shakes
Impact forces



Scenarios

Dry Handling circuit

General Highway road

Deterministic surfaces
Paved surface,
Badly maintained road

Driver in Loop Simulator





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Initial driving simulator session

Objective

Set requirements for OE tire development

Methodology

1. Use reference tire model from "library"
2. Modify tire properties during DS session to understand direction of VD targets

Outcome

Development focus to reach good level of yaw damping and vehicle stability.

Virtual tire submissions

Objective

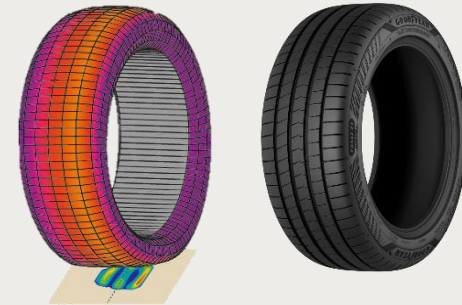
Identify best virtual tire candidates that meet VD targets for Electric Vehicle

Methodology

1. Generate several FE candidates(DOE)
2. Best virtual FEA designs are converted into CD-Tire models
3. CD-Tire models are assessed in the simulator and the best candidate is selected and recommendations are provided for the next virtual loop

Outcome

Final virtual specs for prototype tires to be produced for soft-tool prototype tuning.

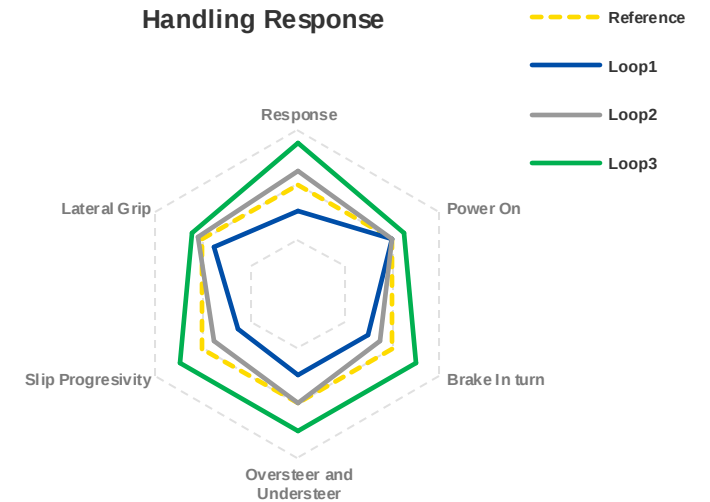
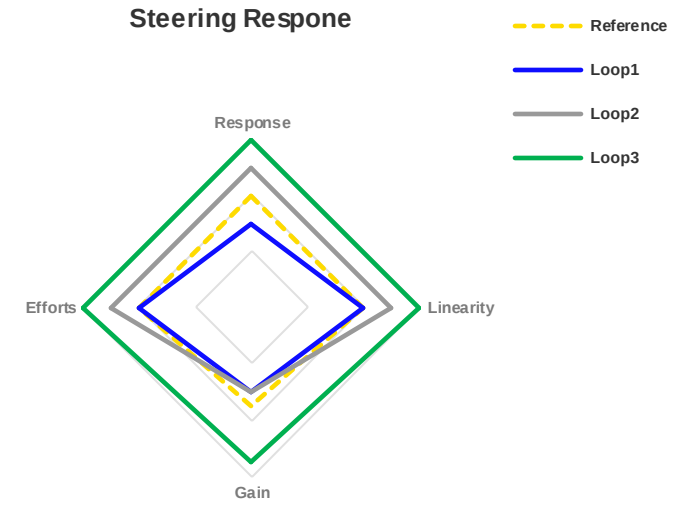
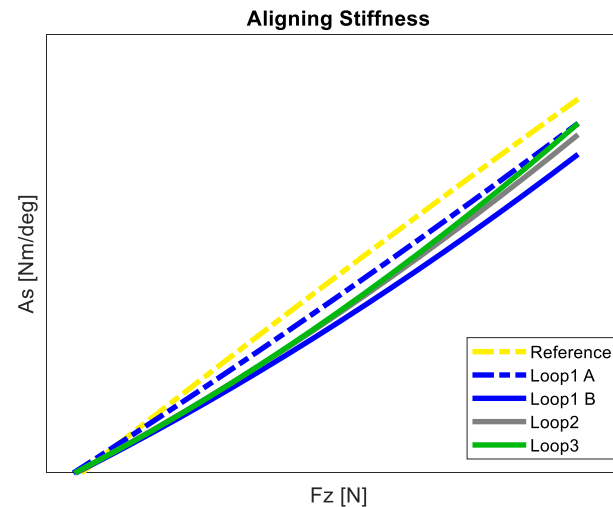
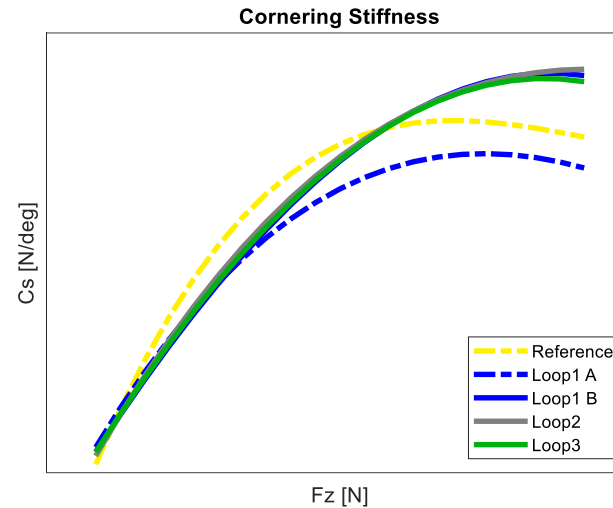


3 Virtual Submissions:

1 Define development direction for BEV and Ride & Handling performance.

2 Vehicle architecture updated. Improvement observed in on-center feeling and vehicle stability. Limit handling predictability to be improved.

3 Vehicle performance targets achieved. Tire characteristics and construction defined for physical build of tire prototypes.



Test	Metric	Ref Tire	Loop 2	Loop 3
Steady-State	SWA gradient	Base	+ 13.00%	+ 19.20%
	Body Sideslip Gradient		- 8.30%	- 25.00%
Frequency Response	YawRate/SWA gain		+ 17.10%	+ 14.40%
	Frequency at max YawRate/SWA gain		+ 18.20%	+ 27.50%

During the different development loops, offline simulations were used to compliment and align with the conclusions observed in the virtual tire evaluation and the subjective feedback obtained in the Driving Simulator.





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MODEL AND PROCESS VALIDATION | ACTIVITY OVERVIEW

1

Kinematics & Compliance testing



Suspension model validation

2

On-track R&H objective testing



Complete vehicle model validation

3

Subjective evaluation



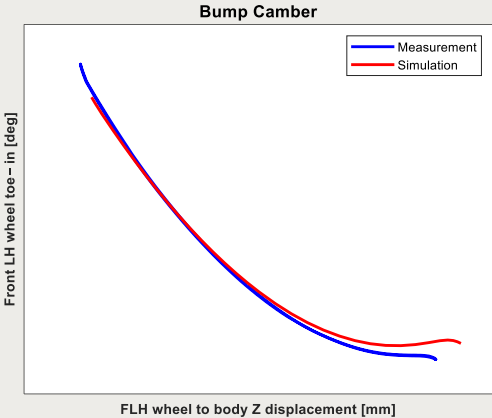
Compare subjective assessment of the real vehicle vs driving simulator



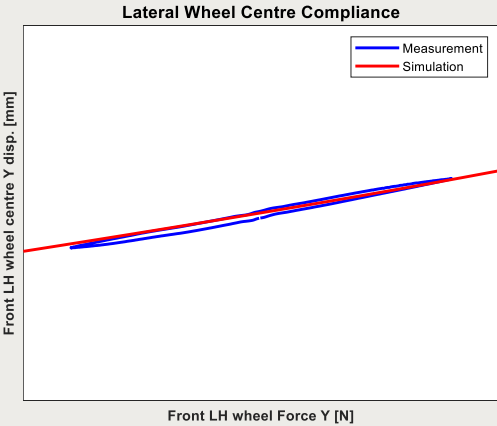
MODEL AND PROCESS VALIDATION

OBJECTIVE VALIDATION RESULTS

SUSPENSION LEVEL

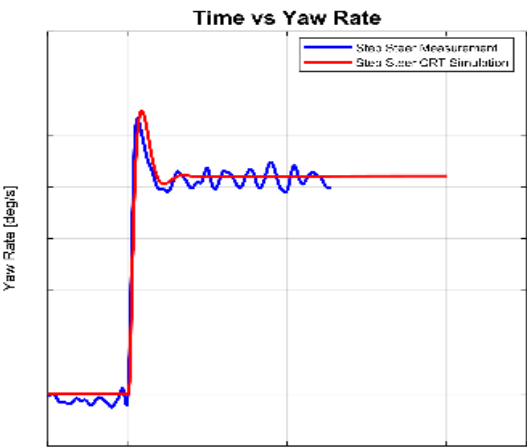


Kinematics
~ 95%

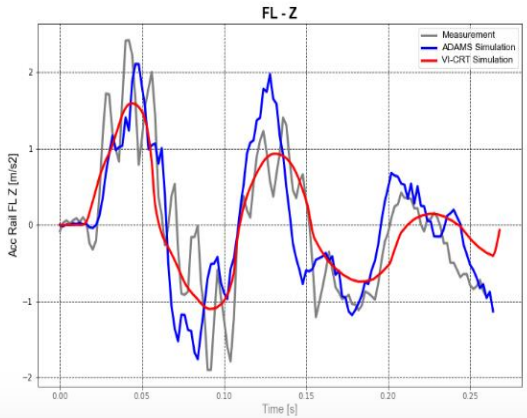


Compliance
~ 95%

COMPLETE VEHICLE LEVEL



Handling & Primary ride
~ 90%



Secondary ride
~ 70%



CONCLUSIONS

- During three virtual submissions using driver-in-loop simulator, a **significant improvement** is observed in vehicle level performance, in terms of handling and steering attributes.
- Good correlation observed between objective measurements on prototype vehicle compared to virtual simulation model.
- Similarly, the tuning engineers confirmed that the behavior of the prototype vehicle was well aligned with the feeling in the simulator.
- This establishes sufficient confidence that **virtual models used are representative of physical behavior** and virtual tire development can successfully be incorporated into mainstream product development life cycle.
- This methodology allows to identify critical areas of improvement for vehicle level performance at an early stage of the project and allows tire manufacturers to define tire characteristics suitable for vehicle requirements.





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THANK YOU

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